

# MSB610L-DC User's Manual



Thank you for your purchase from Comfile Technology

**Before making use of this product please be sure to read and observe all safety precautions.**

## Warning

**⚠ For instruments with risk to life or property (e.g. nuclear power control, medical equipment, vehicles, railways, aviation, combustion equipment, recreation equipment, safety devices, etc.), always employ adequate fail-safe mechanisms.**

- Risk of fire, personal injury, and/or property damage.

- Always mount to a panel.
- Do not attempt to repair, inspect, or wire while power is applied.
- Do not attempt to alter or repair. Refer to a qualified technician.
- Confirm all electrical connections

## Caution

**⚠ Do not use outdoors.**

- Always use the product within its specifications and ratings.
  - Risk of fire and shortening of product's life.
- Do not exceed ratings of relay switching contacts.
- Does not use in environments with flammable or explosive materials, moisture, direct sunlight, radiation, vibration and/or shock.
- Keep product free of dust and debris.
- Make connections correctly and confirm polarity by measuring at the appropriate terminals.

► CE/KCC



**This product is intended for small-scale automation, standalone applications suitable for a Cubloc controller.**

## ◆ About the MSB Series



The Cubloc core module, in semiconductor form, can be mounted to a PCB. This is advantageous, as users can integrate the Cubloc into a custom PCB design in a manner that suits their taste.

However, to a user without PCB fabrication skills, a custom PCB design can be quite difficult. This user must also have the know-how to implement the necessary Input and output circuitry.

The MSB series was designed to make it easy for users to employ the Cubloc without having to have professional PCB fabrication technology and skills.

The MSB series can be installed in the field, have its input and output terminal blocks wired, and can be used just like existing PLCs.

## ◆ MSB User's Manual Composition

For BASIC or Ladder Logic programming, please refer the Cubloc BASIC User's Manual.

This manual only covers those elements unique to the MSB612RA.

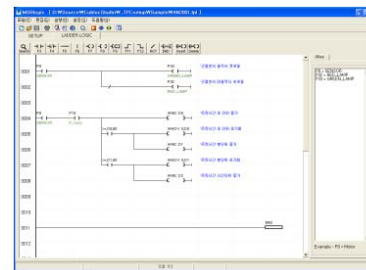
## ◆ CUBLOC STUDIO

To program the MSB series, CUBLOC STUDIO must be used. It can be downloaded from [www.ComfileTech.com](http://www.ComfileTech.com) in the "Cubloc" Support section for free.

## ◆ MSB LOGIC

Originally, the MSB series could only be programmed with CUBLOC Studio, which supports both BASIC and Ladder Logic. However, some users are not familiar with BASIC and prefer to use Ladder Logic exclusively.

Therefore, we have created MSB LOGIC, a Ladder Logic development environment designed specifically for the MSB series. If you prefer to do your development in Ladder Logic, you can now use MSB LOGIC to program the MSB series industrial controllers.



It can be downloaded from [www.ComfileTech.com](http://www.ComfileTech.com) in the "Cubloc" Support section for free.

## ◆ MSB612RA-DC Specifications

The MSB6XX series has a core module equivalent to the Cubloc CB400.

- Program Memory : 200KB
- BASIC Data Memory : 6KB
- Ladder Logic Data Memory : 1KB
- EEPROM Memory : 4KB (Only Accessible in BASIC)
- DC24V Input s: 6 (Port Numbers 8 ~ 13)
- High Capacity Relays (10A): 4 (Port Numbers 32 ~ 35)
- RS232C Communication Port : 1
- No Analog-To-Digital
- Power: 24VDC
- Ambient temperature : -30 to 75 °C
- Humidity : 10% to 90%

## ◆ MSB Usage Declaration

Insert the following at the very beginning of your source code.

```
#include "MSB6XX"
```

## ◆ Download Cable

If your PC has a built-in RS-232C (serial port), it can be used to download programs to the MSB612RA-DC. If not, a USB-to-serial (RS-232C) adapter can be used.

RS-232 3-pin Download Cable	USB-To-Serial + 3-pin Download Cable

Note: The download cable is not included, and must be purchased separately.

If using a USB-to-Serial adapter, you must install the necessary drivers to your PC. After the driver is installed, the PC will assign it a COM port number (e.g. COM6). In Cubloc Studio's PC Interface Setup, select this COM port.

### ◆ BASIC I/O Map

Direction	Range	Input Voltage	Description
Input Port	8 ~ 15	0V or 24VDC (20V to 28V is recognized as a logic high)	1 if input is 24V 0 if input is 0V
Output Port	32 ~ 35	10A Relay Outputs	If 1, Relay is ON If 0, Relay is OFF
Analog Inputs	Ch 0~7	0~3 (0~20mA) 4~7 (0~10V)	Use "ADIn(0~7)" to read input

Example)

```
Low 32 `Turn OFF output port number 32
A = In(10) `Read state of input at port number 10
VA = ADIn(0) `Read analog input from channel 0
```

### ◆ Ladder Logic Memory Map

Designation	Range	Unit	Function
Input Relay P	P0~P31	1 bit	External Input
Output Relay P	P32~P63	1 bit	Relay, etc.. on/off control
Internal Relay M	M0~M511	1 bit	Internal State
Special Purpose Relay F	F0~F127	1 bit	System Status
Timer T	T0~T99	16 bit (1 word)	For Timer
Counter C	C0~C49	16 bit (1 word)	For Counter
Data Region D	D0~99	16 bit (1 word)	Data Storage

By default, all IO is controlled by BASIC at power on. Ladder Logic must be given permission to use it using the UsePin command.

```
Usepin 0, In ` From this point on use P0 in Ladder Logic
Usepin 32, Out ` From this point on, use P32 in Ladder Logic
Set Ladder On ` Place all UsePin commands before enabling Ladder
```

### ◆ Status LED

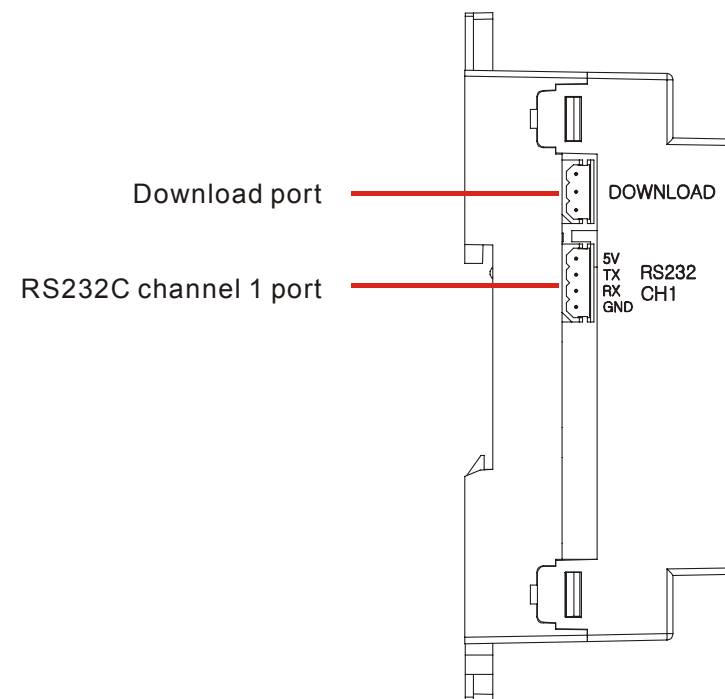
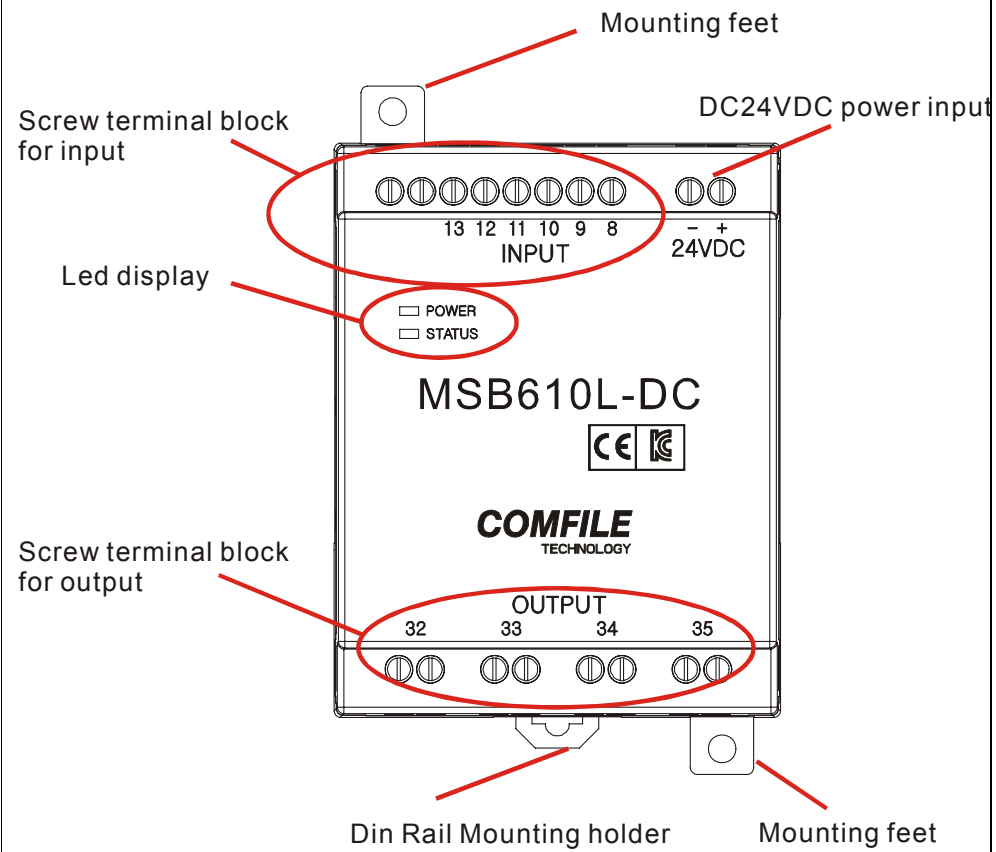
The MSB612RA-DC has a status LED that can be used to indicate the product's operating state. It can be controlled in BASIC using via pin 64.

```
High 64 ` Turn status LED on
Low 64 ` Turn status LED off
```

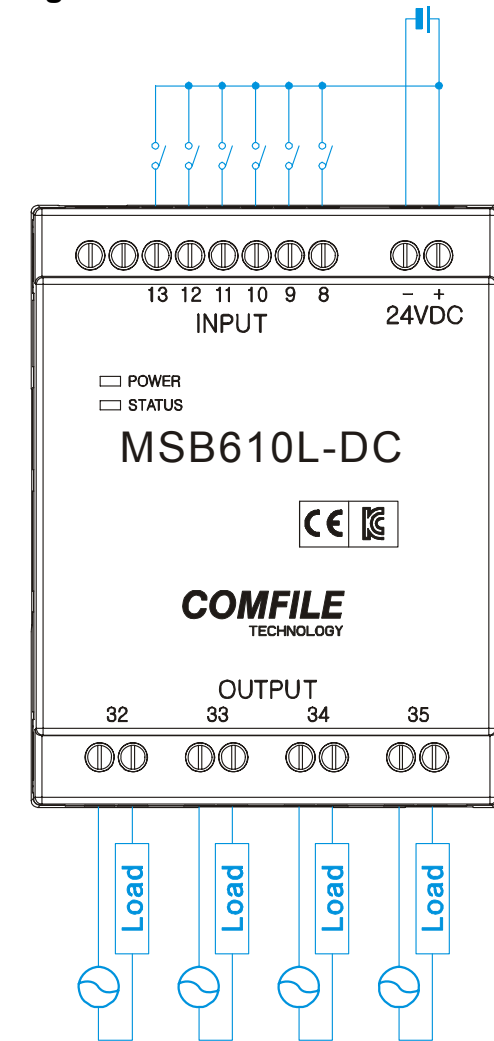
In Ladder Logic, it can be controlled using relay F64.

```
Set Ladder On ` Enable Ladder Scan
_F(64) = 1 ` Turn status LED on
_F(64) = 0 ` Turn status LED off
```

### ◆ Parts Description



### ◆ Digital I/O Wiring



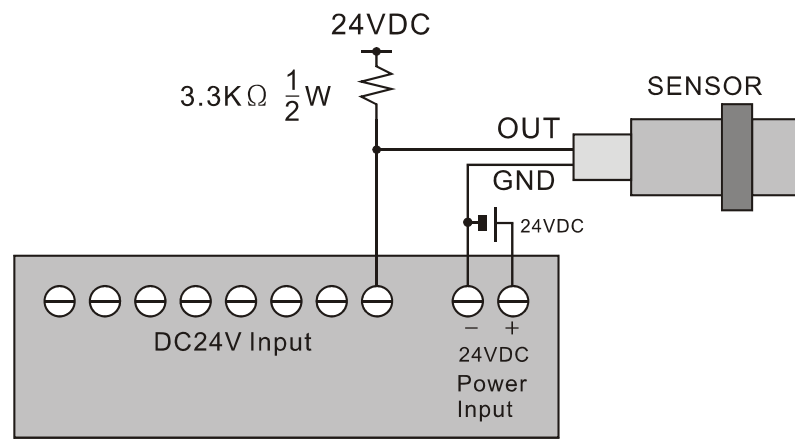


### ◆ Interfacing to Proximity Sensors

Proximity sensors can be used to detect the existence, movement, and displacement of objects without any physical contact with the object. They are used quite often in the field of automation.

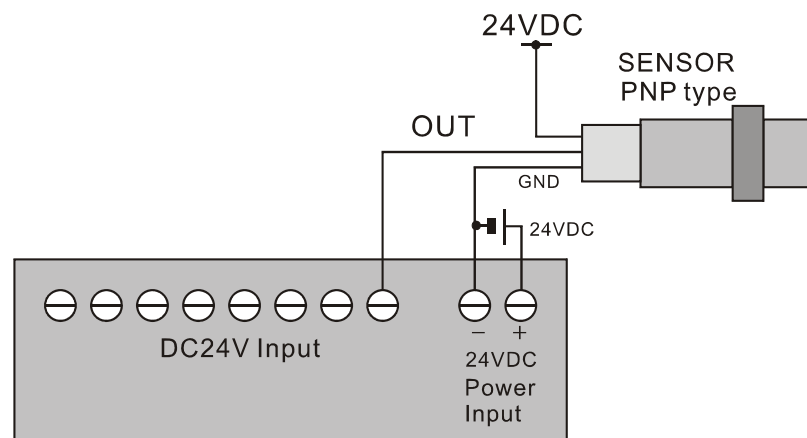
#### DC 2-Wire Model

Sensor output connected in reverse



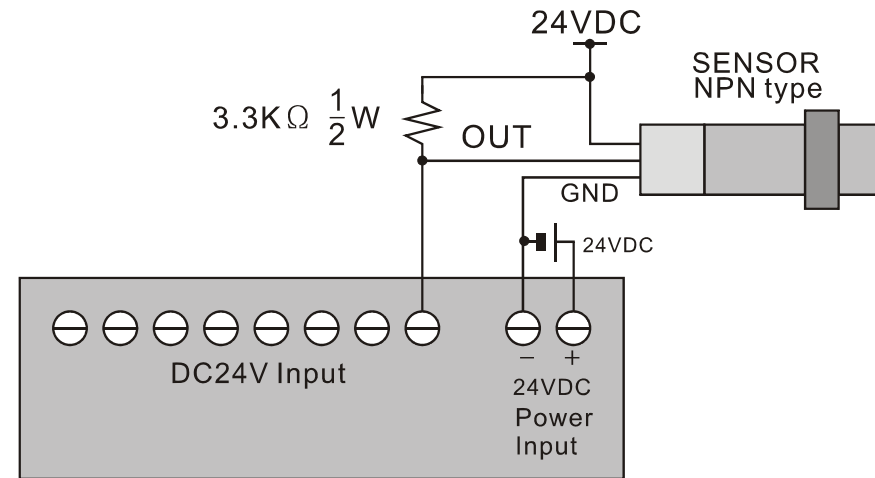
#### DC 3-Wire Model (PNP type)

Sensor output connected in reverse

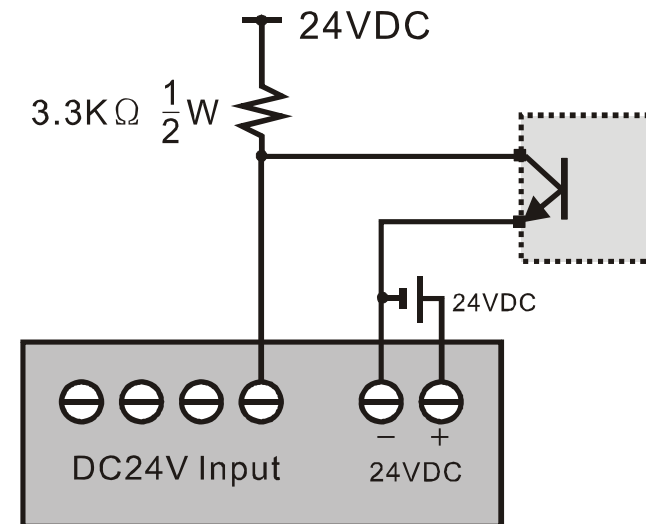


#### DC 3-Wire Model (NPN type)

Sensor output connected in reverse



### ◆ Interfacing with NPN output



### ◆ Digital I/O Specifications

Input Specifications	
Number of Inputs	6
Input Voltage Range	20VDC ~ 28VDC
Recommended Operating Voltage	24VDC
On/Off Switching Speed	10ms (Ladder Scan Time is 10ms)
Input Impedance	2.2kΩ @ 24VDC (Do not connect)

Output Relay Specifications	
Number of Outputs	4
Input Voltage Range	5 ~ 30VDC / 4 ~ 264VAC
Recommended Operating Voltage	6 ~ 27VDC / 6 ~ 240VAC
On/Off frequency	10Hz (10 times per second)
Maximum Current	10A per relay
Minimum Current	100mA per relay

### ◆ Communication Specifications

Communication Port Specifications	
Type	RS-232 (+/- 10VDC)
Flow Control	No RTS Flow Control
Maximum Baud Rate	115200
Maximum Distance	2 meters
Modbus Support	Modbus RTU Slave

## ◆ A Few Simple Examples

### 1. Blinking the Status LED

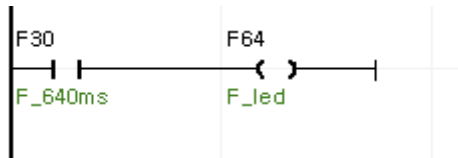
The following program will blink the status LED.

```
#include "MSB6XX"
Do
  High 64
  Wait 500
  Low 64
  Wait 500
Loop
```

Blinking the status LED while using Ladder Logic

```
#include "MSB6XX"
Set Ladder On
Do
  _F(64) = 1
  Wait 500
  _f(64) = 0
  Wait 500
Loop
```

Blinking the status LED from ladder logic



### 2. Toggle Relay

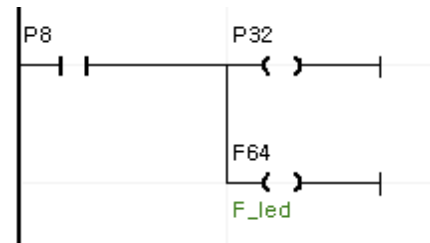
Toggle Status LED and relay number 32.

```
#include "MSB6XX"
Do
  High 64 'Status LED On
  High 32 'Relay 32 On
  Wait 500
  Low 64 'Status LED Off
  Low 32 'Relay 32 off
  Wait 500
Loop
```

### 3. Input and Output Control

If Input 8 is active, the status LED and relay 32 are turn switched on.

```
#include "MSB6XX"
Do
  If In(8) = 1 Then
    High 64 'Status LED On
    High 32 'Relay 32 On
  Else
    Low 64 'Status LED off
    Low 32 'Relay 32 Off
  EndIf
Loop
```



The same behavior using Ladder Logic

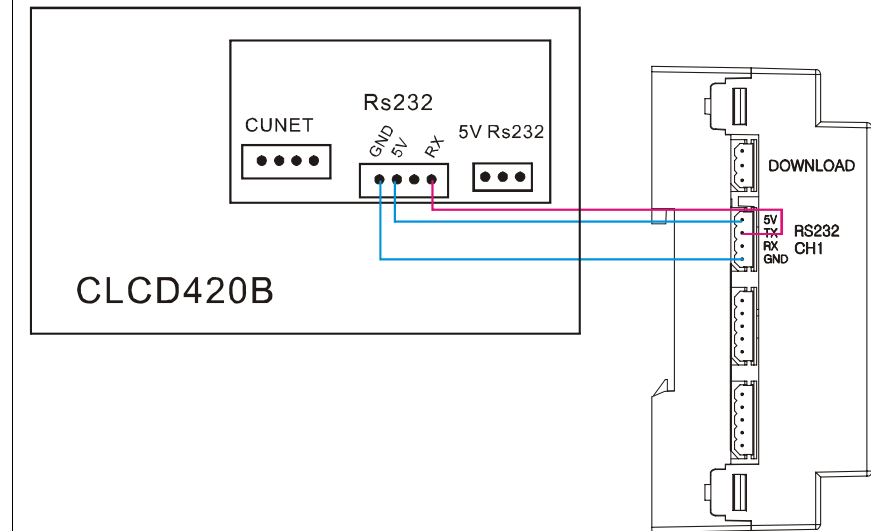
You'll find Ladder Logic to be quite easy for handling simple logic.

## ◆ Interfacing with the UIF-5K

The UIF-5K is a 5-key character LCD panel that can be used in conjunction with the MSB612RA-DC to add a simple user interface.

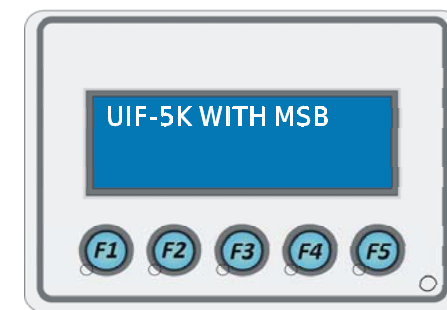


The following shows how to connect the two together. The UIF-5k must be powered separately with a 9V~24V supply.



The following source code will output text to the UIF-5K's display.

```
#include "MSB6XX"
OpenCom 1, 115200, 3, 30, 20
Set UIF 2, 1
Cls
Wait 200
Print 27, 80, 1 ' Buzzer On
CLCDOut 1, 0, "UIF-5K with MSB"
```

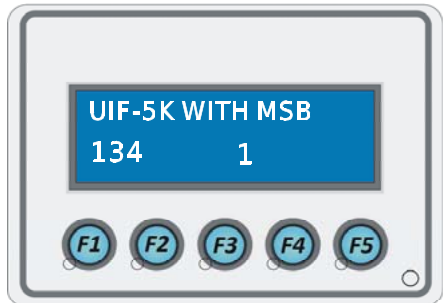


The source code will display a key's scan code when it is pressed.

```
#include "MSB6XX"
OpenCom 1, 115200, 3, 30, 20
Set UIF 2, 1
Cls
Wait 200
Print 27, 80, 1 ' Buzzer On
CLCDOut 1, 0, "UIF-5K with MSB"

Dim I as Integer
Dim RX_KEY as Integer
Do
    Incr I
    CLCDOut 1, 2, Dec I
    Wait 500
Loop

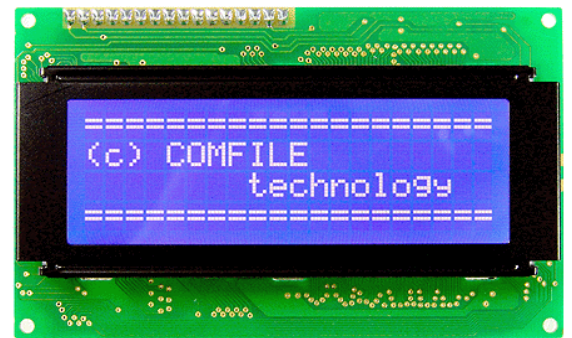
' Key press event handler
KEYIN_OCCUR:
RX_KEY = Get(1, 1)
CLCDOut 10, 2, Hex, RX_KEY
Return
```



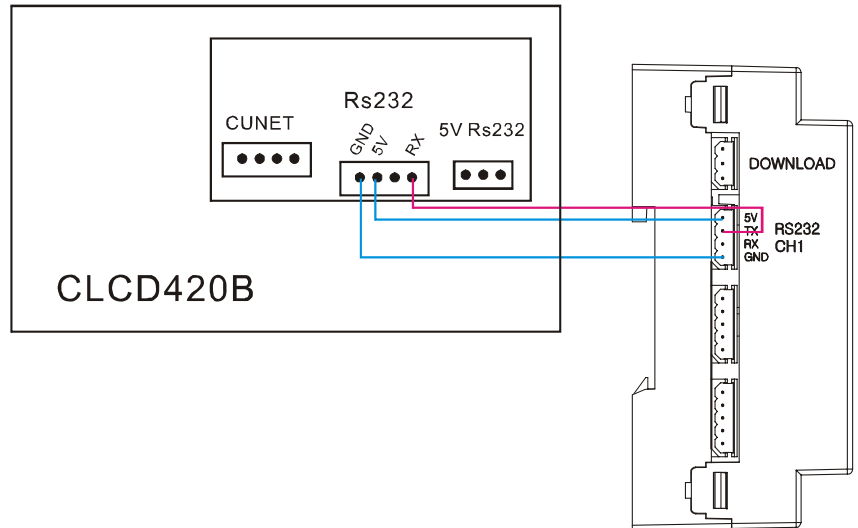
Each time a key is pressed, a receive interrupt occurs via RS-232 and in turn fires the KEYIN\_OCCUR event handler. The event handler reads the scan code and displays it on the character LCD.

### ◆ Interfacing with a CLCD module

A CLCD module is a character LCD module that can be easily interfaced to any Cubloc-based device.



A MSB6XX series device can be connected to a CLCD module via RS-232. Be sure the CLCD's dip switches are on, and the baud rates of both devices are set to 115200. The following shows the wiring.



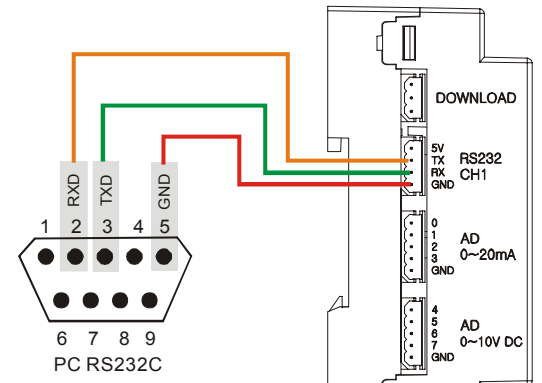
The following source code illustrates how to display text to a CLCD module.

```
#include "MSB6XX"
Set Display 2, 1, 115200, 50
Cls
Wait 200
CLCDOut 1, 0, "CLCD WITH MSB6XX"
```

### ◆ Using Modbus

The following source code illustrates how to use Modbus

```
#include "MSB6XX"
OpenCom 1, 115200, 3, 50, 50
Set Modbus 1, 1, 20
Set Ladder On
Do
Loop
```



The diagram below shows how to connect to a PC. Modbus communication can be tested using CF Term (a free download from [www.ComfileTech.com](http://www.ComfileTech.com)).

**1. Select COM Port and Baud Rate and Open**

**2. Select Modbus RTU, Word Read [03] and Slave Address 1**

**3. Press Send**

**4. Verify Data Received from the MSB**

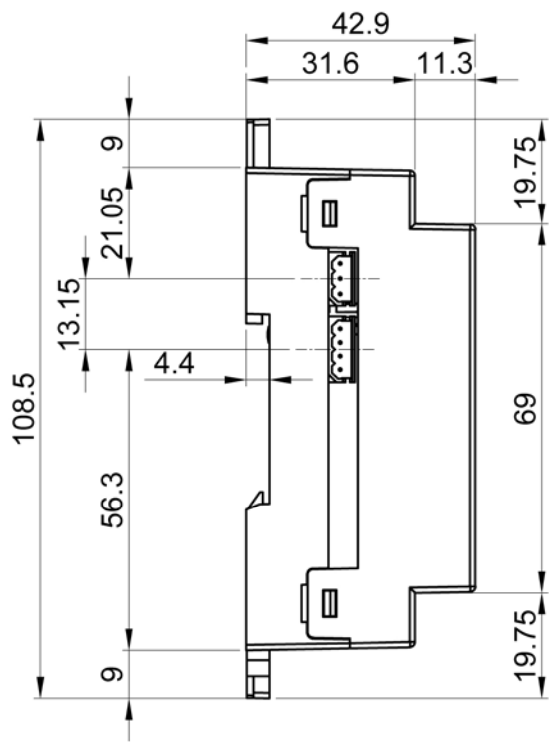
◆ Modbus Address

Word Address

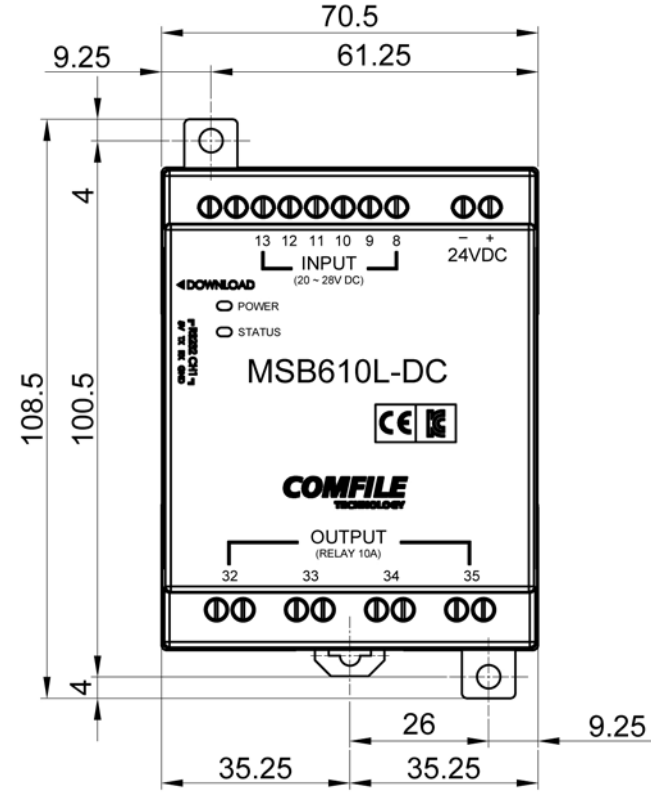
Holding/Input Registers	
Function : 3,4,6,16	
Address	Area
0 ~ 255	D (D0 ~ D255)
256 ~ 355	Y (Y0 ~ Y99) A/D result : Y20~Y27: 276 ~ 283
1000 ~ 1255	T (T0 ~ T255)
2000 ~ 2255	C (C 0~ C255)
3000 ~ 3255	WM (WM0 ~ WM255)

Bit Address

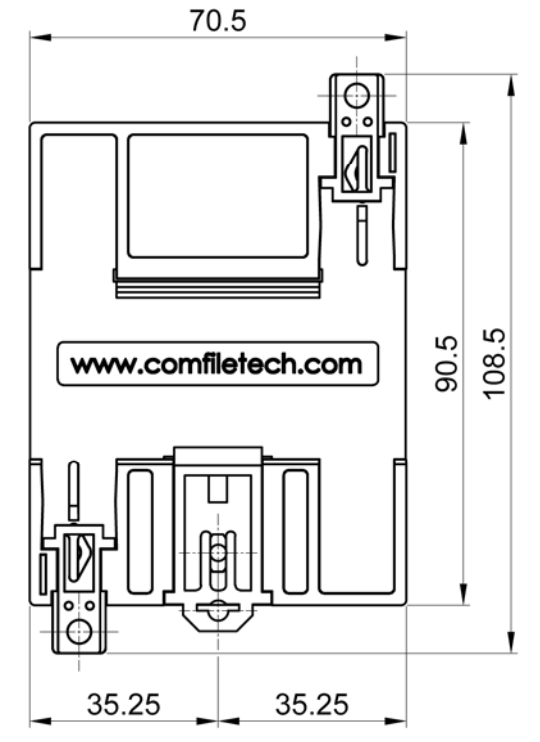
Coil, Input Status	
Function : 1,2,4,15	
Address	Area
0 ~ 127	P (P0 ~ P127)
4096 ~ 6143	M (M0 ~ M2047)



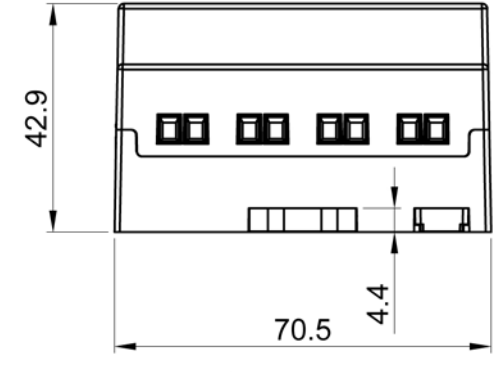
SIDE VIEW



FRONT VIEW



BACK VIEW



BOTTOM VIEW

Unit: mm