**COMFILE Technology** 

www.ComfileTech.com

# MSB612RA-DC User's Manual



Thank you for your purchase from Comfile Technology

Before making use of this product please be sure to read and observe all safety precautions.

#### Warning

- instruments with risk to life or property (e.g. nuclear power control, medical equipment, vehicles, railways, aviation, combustion equipment, recreation equipment, safety devices, etc.), always employ adequate fail-safe mechanisms.
  - Risk of fire, personal injury, and/or property damage.
- 2. Always mount to a panel.
- 3. Do not attempt to repair, inspect, or wire while power is applied.
- 4. Do not attempt to alter or repair. Refer to a qualified technician.
- 5. Confirm all electrical connections

#### Caution

1/1) o not use outdoors.

- 2. Always use the product within its specifications and ratings.
  - Risk of fire and shortening of product's life.
- 3. Do not exceed ratings of relay switching contacts.
- 4. Does not use in environments with flammable or explosive materials, moisture, direct sunlight, radiation, vibration and/or shock.
- 5. Keep product free of dust and debris.
- Make connections correctly and confirm polarity by measuring at the appropriate terminals.

#### ► CE/KCC





# This product is intended for small-scale automation, standalone applications suitable for a Cubloc controller.

#### **◆** About the MSB Series



The Cubloc core module, in semiconductor form, can be mounted to a PCB. This is advantageous, as users can integrate the Cubloc into a custom PCB design in a manner that suits their taste.

However, to a user without PCB fabrication skills, a custom PCB design can be quite difficult. This user must also have the know-how to implement the necessary Input and output circuitry.

The MSB series was designed to make it easy for users to employ the Cubloc without having to have professional PCB fabrication technology and skills.

The MSB series can be installed in the field, have its input and output terminal blocks wired, and can be used just like existing PLCs.

## **♦ MSB User's Manual Composition**

For BASIC or Ladder Logic programming, please refer the Cubloc BASIC User's Manual.

This manual only covers those elements unique to the MSB612RA.

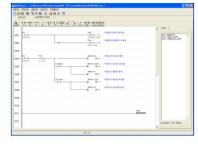
#### **♦** CUBLOC STUDIO

To program the MSB series, CUBLOC STUDIO must be used. It can be downloaded from <a href="www.ComfileTech.com">www.ComfileTech.com</a> in the "Cubloc" Support section for free.

#### **♦ MSB LOGIC**

Originally, the MSB series could only be programmed with CUBLOC Studio, which supports both BASIC and Ladder Logic. However, some users are not familiar with BASIC and prefer to use Ladder Logic exclusively.

Therefore, we have created MSB LOGIC, a Ladder Logic development environment designed specifically for the MSB series. If you prefer to do your development in Ladder Logic, you can now use MSB LOGIC to program the MSB series industrial controllers.



It can be downloaded from  $\underline{\text{www.ComfileTech.com}}$  in the "Cubloc" Support section for free.

#### **♦ MSB612RA-DC Specifications**

The MSB6XX series has a core module equivalent to the Cubloc CB400.

Program Memory : 200KBBASIC Data Memory : 6KB

Ladder Logic Data Memory: 1KB

EEPROM Memory: 4KB (Only Accessible in BASIC)

DC24V Input s: 8 (Port Numbers 8 ~ 15)

High Capacity Relays (10A): 4 (Port Numbers 32 ~ 35)

- RS232C Communication Port: 1

- Analog-To-Digital 10-bit Inputs (0~10V): 4

- Analog-To-Digital 10-bit Inputs (0~20mA): 4

- Power: 24VDC

- Ambient temperature : -30 to 75 °C

- Humidity: 10% to 90%

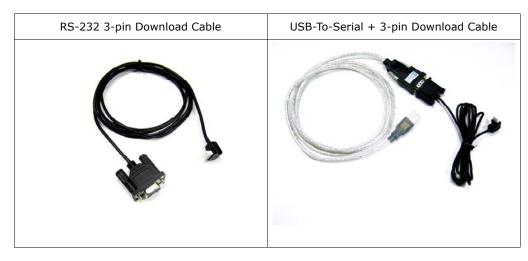
#### **♦ MSB Usage Declaration**

Insert the following at the very beginning of your source code.

#include "MSB6XX"

#### **♦** Download Cable

If your PC has a built-in RS-232C (serial port), it can be used to download programs to the MSB612RA-DC. If not, a USB-to-serial (RS-232C) adapter can be used.



Note: The download cable is not included, and must be purchased separately.

If using a USB-to-Serial adapater, you must install the necessary drivers to your PC. After the driver is installed, the PC will assign it a COM port number (e.g. COM6). In Cubloc Studio's PC Interface Setup, select this COM port.

# **♦** BASIC I/O Map

Direction	Range	Input Voltage	Description
Input Port	8 ~ 15	0V or 24VDC	1 if input is 24V
		(20V to 28V is recognized	0 if input is 0V
		as a logic high)	
Output Port	32 ~ 35	10A Relay Outputs	If 1, Relay is ON
			If 0, Relay is OFF
Analog Inputs	Ch 0~7	0~3 (0~20mA)	Use "ADIn(0~7)" to read
		4~7 (0~10V)	input

#### Example)

Low 32 'Turn OFF output port number 32

A = In(10) 'Read state of input at port number 10

VA = ADIn(0) 'Read analog input from channel 0

#### **♦** Ladder Logic Memory Map

Designation	Range	Unit	Function
Input Relay P	P0~P31	1 bit	External Input
Output Relay P	P32~P63	1 bit	Relay, etc on/off control
Internal Relay M	M0~M511	1 bit	Internal State
Special Purpose Relay F	F0~F127	1 bit	System Status
Timer T	T0~T99	16 bit (1 word)	For Timer
Counter C	C0~C49	16 bit (1 word)	For Counter
Data Region D	D0~99	16 bit (1 word)	Data Storage

By default, all IO is controlled by BASIC at power on. Ladder Logic must be given permission to use it using the UsePin command.

Usepin 0, In 'From this point on use P0 in Ladder Logic
Usepin 32, Out 'From this point on, use P32 in Ladder Logic
Set Ladder On 'Place all UsePin commands before enabling Ladder

#### ◆ Status LED

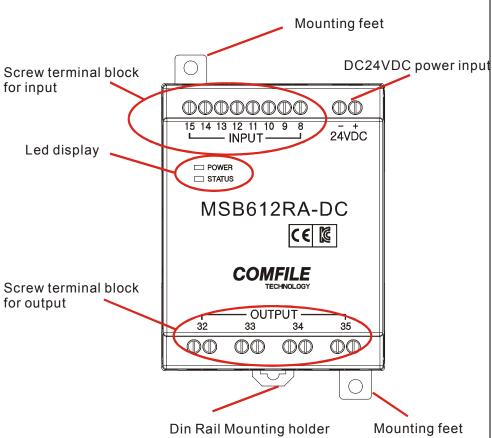
The MSB612RA-DC has a status LED that can be used to indicate the product's operating state. It can be controlled in BASIC using via pin 64.

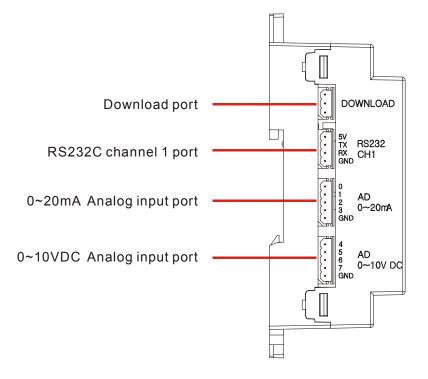
High 64 'Turn status LED on
Low 64 'Turn status LED off

In Ladder Logic, it can be controlled using relay F64.

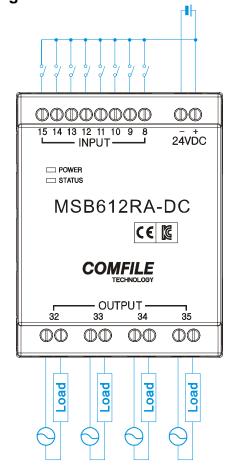
Set Ladder On ' Enable Ladder Scan  $_F(64) = 1$  ' Turn status LED on  $_F(64) = 0$  ' Turn status LED off

# ◆ Parts Description

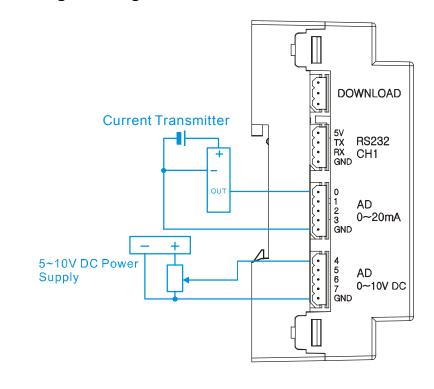




# **♦** Digital I/O Wiring



## ♦ Analog I/O Wiring



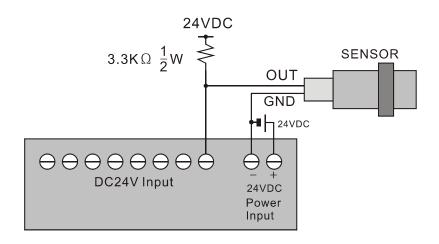


### **♦** Interfacing to Proximity Sensors

Proximity sensors can be used to detect the existence, movement, and displacement of objects without any physical contact with the object. They are used quite often in the field of automation.

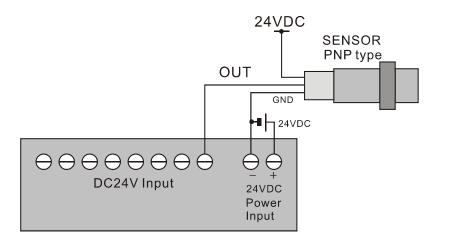
# DC 2-Wire Model

Sensor output connected in reverse



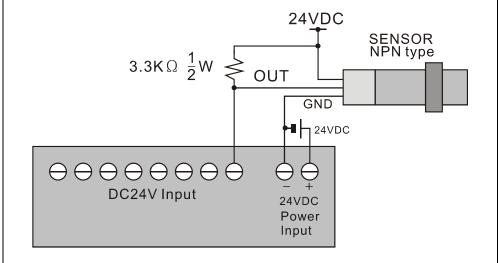
# DC 3-Wire Model (PNP type)

Sensor output connected in reverse

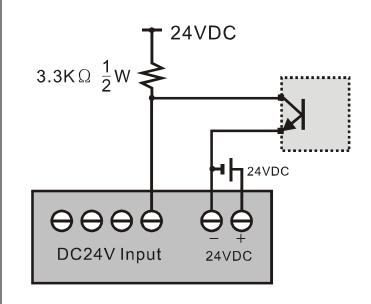


# DC 3-Wire Model (NPN type)

Sensor output connected in reverse



## ◆ Interfacing with NPN output



## ◆ Digital I/O Specifications

Input Specifications		
Number of Inputs	8	
Input Voltage Range	20VDC ~ 28VDC	
Recommended Operating Voltage	24VDC	
On/Off Switching Speed	10ms (Ladder Scan Time is 10ms)	
Input Impedance	2.2kΩ @ 24VDC (Do not connect)	

Output Relay Specifications		
Number of Outputs	4	
Input Voltage Range	5 ~ 30VDC / 4 ~ 264VAC	
Recommended Operating Voltage	6 ~ 27VDC / 6 ~ 240VAC	
On/Off frequency	10Hz (10 times per second)	
Maximum Current	10A per relay	
Minimum Current	100mA per relay	

### **♦** Analog I/O Specifications

Analog Current Input (0 ~ 3) Specification		
Resolution and Error	10-bit, +/- 2%	
Input Current Range	0mA ~ 22mA	
Recommended Operating Current	4mA ~ 20mA	
Туре	Non-isolated, Built-in LPF	

Analog Voltage Input (4 ~ 7) Specifications	
Resolution and Error	10-bit, +/- 2%
Input Voltage Range	-0.5VDC ~ 10.5VDC  Don't connect series resistance
Operating Voltage	0VDC ~ 10VDC
Туре	Non-isolated, Built-in LPF

## **♦** Communication Specifications

Communication Port Specifications		
Туре	RS-232 (+/- 10VDC)	
Flow Control	No RTS Flow Control	
Maximum Baud Rate	115200	
Maximum Distance	2 meters	
Modbus Support	Modbus RTU Slave	

#### **♦** A Few Simple Examples

#### 1. Blinking the Status LED

The following program will blink the status LED.

```
#include "MSB6XX"

Do
    High 64
    Wait 500
    Low 64
    Wait 500
Loop
```

Blinking the status LED while using Ladder Logic

```
#include "MSB6XX"
Set Ladder On
Do
    _F(64) = 1
    Wait 500
    _f(64) = 0
    Wait 500
Loop
```

Blinking the status LED from ladder logic

```
F30 F64
F_640ms F_led
```

#### 2.Toggle Relay

Toggle Status LED and relay number 32.

```
#include "MSB6XX"

Do

High 64 'Status LED On

High 32 'Relay 32 On

Wait 500

Low 64 'Status LED Off

Low 32 'Relay 32 off

Wait 500

Loop
```

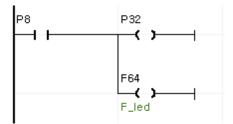
## 3. Input and Output Control

If Input 8 is active, the status LED and relay 32 are turn switched on.

```
#include "MSB6XX"
Do

If In(8) = 1 Then
    High 64 'Status LED On
    High 32 'Relay 32 On

Else
    Low 64 'Status LED off
    Low 32 'Relay 32 Off
EndIf
Loop
```



The same behavior using Ladder Logic

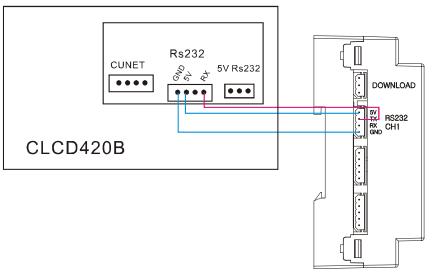
You'll find Ladder Logic to be quite easy for handling simple logic.

#### ◆ Interfacing with the UIF-5K

The UIF-5K is a 5-key character LCD panel that can be used in conjunction with the MSB612RA-DC to add a simple user interface.



The following shows how to connect the two together. The UIF-5k must be powered separately with a  $9V\sim24V$  supply.



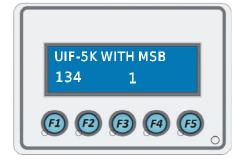
The following source code will output text to the UIF-5K's display.

```
#include "MSB6XX"
OpenCom 1, 115200, 3, 30, 20
Set UIF 2, 1
Cls
Wait 200
Print 27, 80, 1 ' Buzzer On
CLCDOut 1, 0, "UIF-5K with MSB"
```



The source code will display a key's scan code when it is pressed.

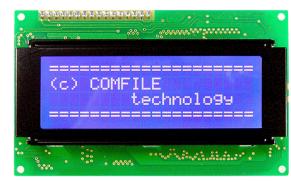
```
#include "MSB6XX"
OpenCom 1, 115200, 3, 30, 20
Set UIF 2, 1
Cls
Wait 200
Print 27, 80, 1 ' Buzzer On
CLCDOut 1, 0, "UIF-5K with MSB"
Dim I as Integer
Dim RX_KEY as Integer
Do
   Incr I
   CLCDOut 1, 2, Dec I
  Wait 500
Loop
 Key press event handler
KEYIN_OCCUR:
RX_KEY = Get(1, 1)
CLCDOut 10, 2, Hex, RX_KEY
```



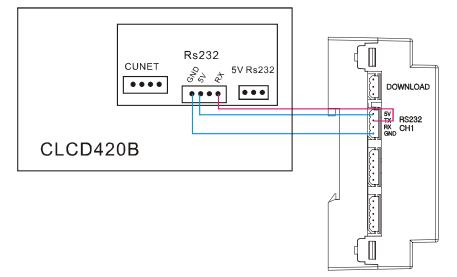
Each time a key is pressed, a receive interrupt occurs via RS-232 and in turn fires the KEYIN\_OCCUR event handler. The event handler reads the scan code and displays it on the character LCD.

## ◆ Interfacing with a CLCD module

A CLCD module is a character LCD module that can be easily interfaced to any Cubloc-based device.



A MSB6XX series device can be connected to a CLCD module via RS-232. Be sure the CLCD's dip switches are on, and the baud rates of both devices are set to 115200. The following shows the wiring.



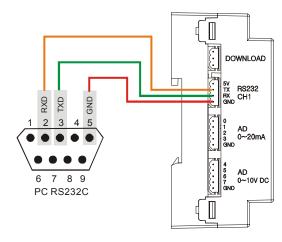
The following source code illustrates how to display text to a CLCD module.

```
#include "MSB6XX"
Set Display 2, 1, 115200, 50
Cls
Wait 200
CLCDOut 1, 0, "CLCD WITH MSB6XX"
```

#### Using Modbus

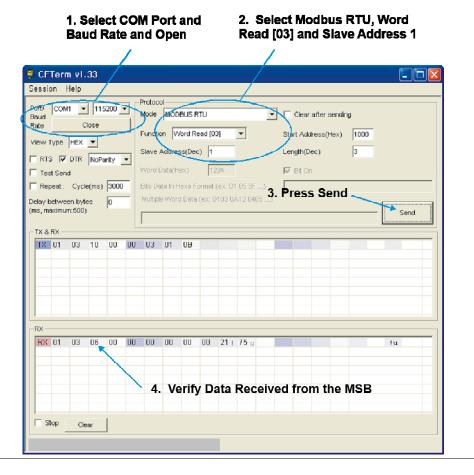
The following source code illustrates how to use Modbus

```
#include "MSB6XX"
OpenCom 1, 115200, 3, 50, 50
Set Modbus 1, 1, 20
Set Ladder On
Do
Loop
```



The diagram below shows how to connect to a PC.

Modbus communication can be tested using CF Term (a free download from <a href="https://www.comfileTech.com">www.comfileTech.com</a>).



# ◆ Analog Input Example

The following source code illustrates how to use analog inputs. Results are displayed in the PC's debug terminal.

For channels  $0 \sim 3$  ( $0 \sim 20$ mA).

```
#include "MSB6XX"
Dim AD as Integer
Do
    AD = ADIn(0) 'Read from channel 0
    Debug Dec AD, Cr
    Delay 1000
Loop
```

For channels  $4 \sim 7 (0 \sim 10 \text{VDC})$ .

```
#include "MSB6XX"
Dim AD as Integer
Do
    AD = ADIn(4) 'Read from channel 4
    Debug Dec AD, Cr
    Delay 1000
Loop
```

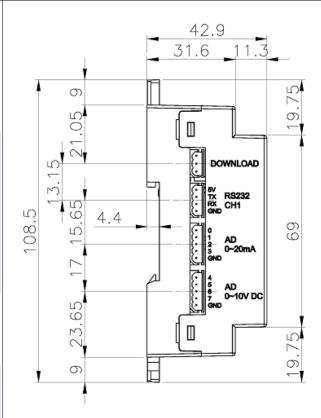
## **♦** Modbus Address

#### Word Address

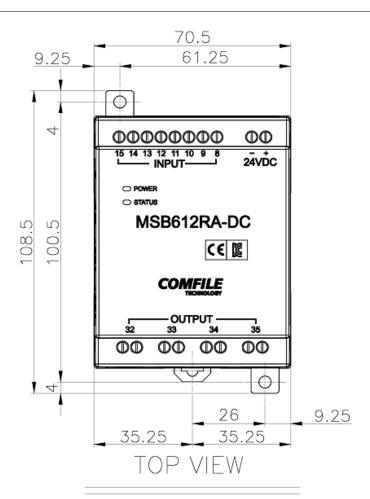
Holding/Input Registers		
Function: 3,4,6,16		
Address	Area	
0 ~ 255	D (D0 ~ D255)	
256 ~ 355	Y (Y0 ~ Y99)	
	A/D result :	
	Y20~Y27: 276 ~283	
1000 ~ 1255	T (T0 ~ T255)	
2000 ~ 2255	C (C 0~ C255)	
3000 ~ 3255	WM (WM0 ~ WM255)	

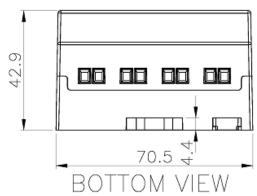
## Bit Address

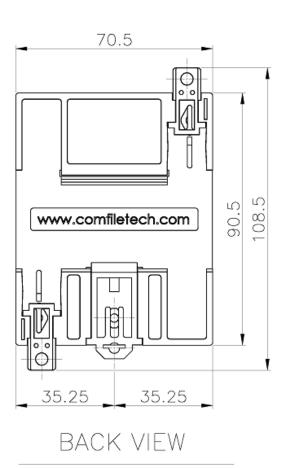
Coil, Input Status	
Function: 1,2,4,15	
Address	Area
0 ~ 127	P (P0 ~ P127)
4096 ~ 6143	M (M0 ~ M2047)



SIDE VIEW







Unit: mm